Mixed-precision orthogonalization process Performance on multicore CPUs with GPUs

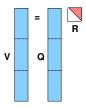
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TSQR: Tall-Skinny QR

orthogonalizes a set of dense columns vectors V (m-by-n, $m \gg n$),



where Q is a set of orthogonal vectors, and R is upper triangular.

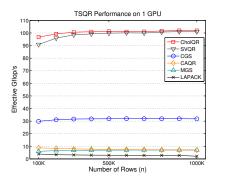
- important computational kernels:
 - ▶ 1st part of this talk: n = O(10) "Communication-avoiding" Krylov (n = s)
 - ▶ 2nd part of this talk: n = O(100)Random sampling for low-rank matrix approximation $(n = k + \ell)$

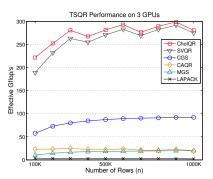
TSQR Algorithms

Many ways to compute TSQR:

- Householder QR (with O(s) reductions)
 Householder transform each column based on BLAS-1,2 xGEQR2
- Modified Gram-Schmidt (with O(s) reductions)
 ortho each column against each column based on BLAS-2,1 xGEMV, xDOT
- Classical Gram-Schmidt (with O(s) reductions)
 ortho each column against prev columns based on BLAS-2,1 xGEMV, xDOT
- Cholesky QR (or SVQR) (with O(1) reductions)
 ortho all columns against prev columns based on BLAS-3 xGEMM, xTRSM
- CAQR (with O(1) reductions)
 ortho all columns against prev columns based on tree-reduction BLAS-1.2 xGEQR2

TSQR Performance (16-core SandyBridge with three M2090 Fermi, s = 30)

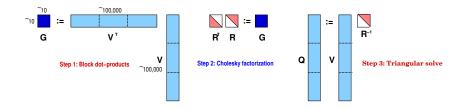




- ► CholQR shows superior performance based on BLAS-3
- performance depends more on intra-comm (BLAS performance) than on inter-comm.
- it scales well over 3 GPUs.

CholQR factorization for *TSQR* [A. Stathopoulos and K. Wu. 2002]

- Step 1 Gram-matrix formation $G := V^T V$ ($\frac{1}{2}ns^2$ ops on GPUs).
- Step 2 Cholesky factorization $R^TR := G$ $(\frac{1}{6}s^3 \text{ ops on CPUs}).$
- Step 3 Backward-substitution $Q := VR^{-1}$ ($\frac{1}{2}ns^2$ ops on GPUs).



- Most of flops using BLAS-3.
- Only a pair of global communication (reduction+broadcast).

TSQR Stability:

- trade-off between performance and stability
 - CholQR performs most of computation using BLAS-3.
 - Condition number of Gram matrix G is square of A.

	$ I - Q^T Q $	# flops, GPU kernel	# GPU-CPU comm.
MGS	$O(\epsilon \kappa(V))$	2ns ² , BLAS-1 xDOT	$O(s^2)$
CGS	$O(\epsilon \kappa (V)^{s-1})$	2 <i>ns</i> ² , BLAS-2 xGEMV	O(s)
CholQR	$O(\epsilon \kappa(V)^2)$	2ns ² , BLAS-3 xGEMM	O(1)
SVQR	$O(\epsilon \kappa (V)^2)$	2 <i>ns</i> ² , BLAS-3 xGEMM	O(1)
CAQR	$O(\epsilon)$	4ns ² , BLAS-1,2 xGEQR2	O(1)

- it often requires reorthogonalization
- it could fail if $\kappa(V) > \epsilon^{-1/2}$.

Mixed Precision CholQR

- ▶ Remove "square" in error bound by selectively using "doubled" precision:
 - Step 1 Gram-matrix formation $G := V^T V$ (V in double) doubled-precision on GPUs.
 - Step 2 Cholesky factorization $R^T R := G$ doubled-precision on CPUs.
 - Step 3 Backward-substitution $Q := VR^{-1}$ working-precision on GPUs.



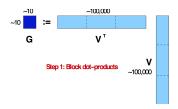
- \rightarrow orthogonality error depends linearly on $\kappa(V)$ (more details in SISC paper, submitted) $||I Q^T Q|| \le O(\epsilon \kappa(V) + (\epsilon \kappa(V))^2)$ and $||Q|| \le 1 + O(\epsilon \kappa(V))$
- ightarrow may require software-emulated arithmetics for doubled-precision
 - e.g., for working double, double-double to emumerate quadruple precision computation increases by $8.5 \times$ [Y. Hida, X. Li, and D. Bailey, '00], but communication-bounded, $\frac{1+n}{2}$ flops per read read V in double, only volume doubles to form $G_{\square} \times \mathbb{R} \times \mathbb{R} \times \mathbb{R}$

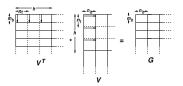
Batched GPU kernels for block inner-products

"batched" xGEMM/xSYRK kernel

- 1. thread block to compute partial block product
- 2. local reduction to compute partial Gram matrix
- 3. global all reduce to form final Gram matrix

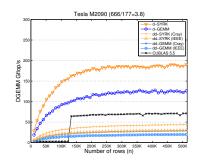
brute-force tune for dimension and precision on GPU (by Tim Dong)

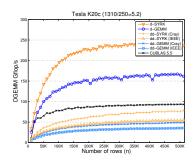




Block inner-products in double-double vs. double precision

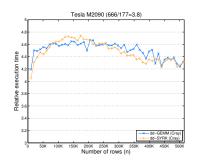
- optimized batched xGEMM kernel for block inner-product, $n = O(10^5)$, s = O(10).
 - ► 1.7× speedups over CUBLAS 5.5 for d-precision. 30% of the peak based on memory bandwidth
 - ▶ 16× more ops for dd-precision (Cray).
 - input matrix in d-precision, compute intermediate results in dd-precision

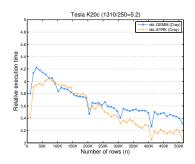




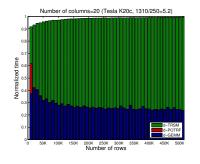
Block inner-products in double vs. double-double precision

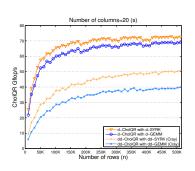
- optimized batched xGEMM kernel for block inner-product, $n = O(10^5)$, s = O(10).
 - ▶ 1.7× speedups over CUBLAS 5.5 for d-precision.
 - ▶ 16× more ops for dd-precision (Cray).
 - memory-bound operation.
 - \rightarrow 4.5× or 3.5× slower on Fermi or Kepler.





Mixed Precision CholQR Performance



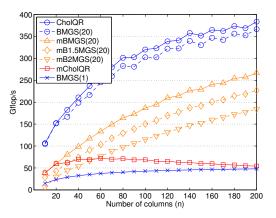


- only about 30% of d-CholQR in d-GEMM.
- ▶ dd-CholQR 8.5× ops, but 1.7× slower than d-CholQR
 - dd-CholQR may be competitive with 2×d-CholQR d- or dd-CholQR could fail if $\kappa(V)>\epsilon^{-1/2}$ or $>\epsilon^{-1}$
- CA-Krylov performance can be improved
 - reduced orthogonalization time, larger step size, or faster convergence

Extension to orthogonalize many columns

- ▶ Motivation: random sampling of large sparse matrix, n = O(100)
- ► CholQR performs $\frac{1+n}{2}$ flops on each numerical value read.
- As n increases,
 - it becomes more compute-bound
 - mixed-precision CholQR becomes slower
- Use mixed-precision CholQR within block MGS
 - BMBS and then CholQR same bound by using mCholQR+CholQR with comp. overhead of $\frac{8.5}{n_t} \times$
 - restarted CA-Krlov to orthogonalize s vectors of m vectors at a time

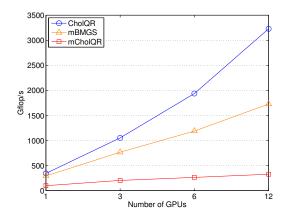
Performance of BMGS: m = 100,000 on one GPU



with n = 200.

- ▶ mCholQR was $7.1 \times$ slower than CholQR (with $8.5 \times$ ops)
- ▶ mB1.5MGS was $1.7 \times$ slower than CholQR (with $1.8 \times$ ops) and was $4.1 \times$ faster than mCholQR

Performance of BMGS: (m, n) = (500, 000, 200) on multiple GPUs



compared to CholQR,

- ▶ B1.5MGS communicates $n_t \times$ more
- mCholQR has greater bottleneck with ddPOTRF

Final Remarks

- Mixed-precision CholQR
 - performs 8.5× more computation
 - reduces $2 \times$ more words, $O(n^2)$ with $n \ll m$
 - was $1.4 \times$ slower when n = O(10)
 - was $7.1 \times$ slower when n = O(100)
 - smaller overhead if supported by hardware (e.g., single)
- BMGS combined with dd-CholQR + d-CholQR
 - ▶ performs $\frac{8.5}{n_t}$ × more computation, where n_t is number of block columns
 - was $1.7 \times$ slower when n = O(100)
 - ightharpoonup communicates $n_t \times$ more often

Current Work

- Numerical studies and theoretical bounds
- ► CAQR based on batched QR
 [J. Demmel, L. Grigori, M. Hoemmen, J. Langou, 2012]

Thank you!!